2020

COMPUTER SCIENCE — HONOURS

Paper: SEC-A-1

(Computer Graphics)

Full Marks: 80

The figures in the margin indicate full marks.

Candidates are required to give their answers in their own words as far as practicable.

Answer question no. 1 and any four from the rest.

1. Answer any ten questions:

 2×10

- (a) What do you understand by point clipping?
- (b) Write the two dimensional scaling matrix (about x-axis and about y-axis).
- (c) Define raster scan.
- (d) Mention the importance of homogeneous coordinate system.
- (e) What do you understand by resolution of a monitor?
- (f) Write down the three-dimensional translation matrix.
- (g) Give the fundamental difference between animation and morphing.
- (h) Define view port and window port.
- (i) Define world coordinate system.
- (i) Mention the importance of inverse transformation.
- (k) State the purpose of any clipping algorithm.
- (l) Differentiate between perspective projection and parallel projection.
- (m) Transformation depends on reference point. Justify your answer.
- (n) Briefly discuss about LCD display system.
- **2.** (a) Discuss and derive Midpoint line drawing algorithm.
 - (b) Discuss and derive Digital Differential Analyzer scan conversion line drawing algorithm.
 - (c) Mention the advantages of Midpoint line drawing algorithm over Digital Differential Analyzer.

5+5+5

3. (a) Write the two dimensional reflection matrix—reflection about x-axis, reflection about y-axis and reflection about origin.

Please Turn Over

(b) Show that scaling followed by rotation and rotation followed by scaling are commutative with some conditions.

(2)

- (c) Derive the matrix in two-dimension for reflection of an object about a line y = 2x. $(2\times3)+5+4$
- **4.** (a) ABCD is a square with coordinate points A(0, 4), B(4, 4), C(4, 0) and D(0, 0). Apply translation with distance 2 towards x-axis and 2 towards y-axis. Obtain the new coordinates of the square.
 - (b) What do you understand by Affine transformation?
 - (c) ABC is a triangle with coordinate points A(2, 2), B(4, 2) and C(4, 4). Find the rotation matrix after applying rotation with an angle 90° about origin in anti-clockwise direction. Find the new coordinates after rotation.

 5+2+(4+4)
- 5. (a) Derive and discuss Bresenham's line drawing algorithm.
 - (b) Discuss Sutherland Hudgeman polygon clipping algorithm with an example.
 - (c) Apply the Cohen-Sutherland line clipping algorithm to clip the line segment AB with coordinate points A(40, 50) and B(50, 70) against the window (30, 60) and (60, 100). 5+5+5
- **6.** (a) Show that the 2×2 matrix T such that

$$[T] = \begin{bmatrix} \frac{1-t^2}{1+t^2} & \frac{2t}{1+t^2} \\ \frac{-2t}{1+t^2} & \frac{1-t^2}{1+t^2} \end{bmatrix}$$

represents pure rotation.

- (b) Let (x_1, y_1, w_1) and $(x_2, y_2, 1)$ be the homogeneous coordinate representation of points P_1 and P_2 , respectively and let $(x'_1, y'_1, 1)$ be the homogeneous coordinates of P'_1 a point obtained after rotating P_1 around P_2 by α degrees. Express x'_1 and y'_1 in terms of $x_1, y_1, w_1, x_2, y_2, \alpha$.
- (c) Briefly write about keyframes and in-between as used in animation.
- 5+5+5

- 7. (a) Derive and discuss Midpoint circle drawing algorithm.
 - (b) Discuss eight-way symmetry circle drawing algorithm.
 - (c) Mention the disadvantages of scan converting circle drawing algorithm over Midpoint circle drawing algorithm.

 5+5+5
- **8.** (a) Apply Cohen-Sutherland line clipping algorithm to check whether the following line segments are totally visible against the window (20, 40) and (60, 80).
 - (i) line segment AB with coordinates A(30, 50), B(50, 60).
 - (ii) line segment CD with coordinate C(10, 10), D(20, 10).
 - (iii) line segment EF with coordinate E(40, 50), F(50, 85).
 - (b) Discuss about interior clipping and exterior clipping.

 $(4 \times 3) + 3$